**MANIPULATION PROTOCOL TEMPLATE**

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| Reference No / Version |  |
| Authors |  |
| Institution |  |
| Contact information |  |
| Purpose  |  |
| Task Description  |  |
| Setup Description  | List of objects and their descriptions: |
| Initial and target poses of the objects: |
| Description of the manipulation environment: |
| Robot/Hardware/Software/Subject Description | Targeted robots/hardware/software: |
| Initial state of the robot/hardware/subject with respect to the setup: |
| Prior information provided to the robot: |
| Procedure |  |
| Execution Constraints |  |